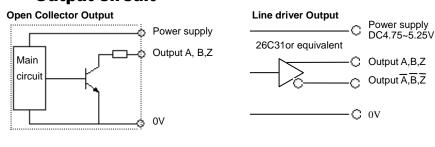


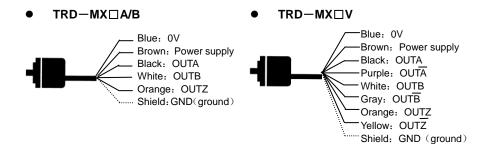
Electrial specifications

Type No.

Output circuit



Connection



| | 21 | | | | |
|-------------------------|-----------------------------------|---------|---|---------------------------------------|--|
| | Operating voltage ^{*1} | | A: 4.5V~13.2V DC | 4.75V~5.25V DC | |
| Power | | | B: 10.8V~26.4V DC | | |
| supply Allowable ripple | | pple | 3%rms Max. | 3%rms Max. | |
| | Current consumption(no load) | | 50mA Max. | 50mA Max. | |
| | Signal format | | Quadrature output | Quadrature output | |
| Output waveform | Max. response frequency | | 100kHz | 100kHz | |
| | Operating speed | | (Maximum response frequency/Pulse) $	imes$ 60 | (Maximum response frequency/Pulse)×60 | |
| | Symmentry | | 50±25% | 50±25% | |
| | Index signal width | | 100±50% | 100±50% | |
| Output | Rising/falling time ^{*2} | | 2µs Max. | 2µs Max. | |
| | Output configuration | | NPN open collector | Line driver (26C31 or equivalent) | |
| | Output logic | | Negative logic (active low) | Positive logic (active high) | |
| | Output current | Inflow | 30mA Max. | | |
| | | Outflow | _ | 20mA Max. | |
| | | "H" | _ | 2.5V Min. | |
| | Output voltage | "L" | 0.4V Max. | 0.5V Max. | |
| | Load power supply voltage | | DC30V Max. | _ | |

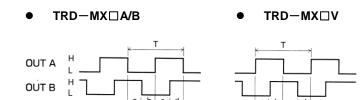
TRD-MX A/B

*1: To be supplied by class $I\!I$ source

*2: With a cable of 1m or less.Maximum load.

Output signal timing chart

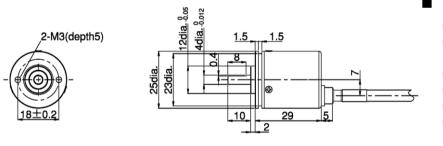
(CW rotation viewed from input-shaft of encoder)



a,b,c,d=(25±12.5%)T

External dimensions

OUT Z



Mechanical specifications

| Startin | Max. 0.001N • m (+20°C) | | |
|---------------------------|--|---------------------------------|--|
| Shaft mom | $1 \times 10^{-7} \mathrm{kg} \cdot \mathrm{m}^2$ | | |
| | Radial | 10N | |
| Max. allowable shaft load | Thrust | 5N | |
| Max.allow | 6000rpm | | |
| | Material | Oil-resistant PVC ^{*3} | |
| Cable | Nominal core cross section | 0.14mm ² | |
| | External diameter | 5.0mm | |
| We | Approx.0.08kg*4 | | |

^{*3} MX A/B: 5-core shielded cable (AWG26)

 $\mathsf{MX} \square \mathsf{V}~$: 8-core shidlded cable (AWG26)

*4 with 1m cable

Cautions for use

- Do not wire the cable in parallel with other power lines and do not share a duct with other cables.
- Use capacitors or surge absorption elements to remove the sparks caused by relays and switches in the control panel as far as possible.
- Be sure to connect all wires properly, as wrong wiring can damage the internal circuitry.
- Erroneous pulses may be caused at the time of power ON and power OFF. After power ON, wait for at least 0.5 sec before use. Do not disassemble the product.
- As the rotary encoder is composed of precision parts, its function will be impaired when it is subjected to shocks. Use sufficient care for handling and mounting.

Environmental requirements

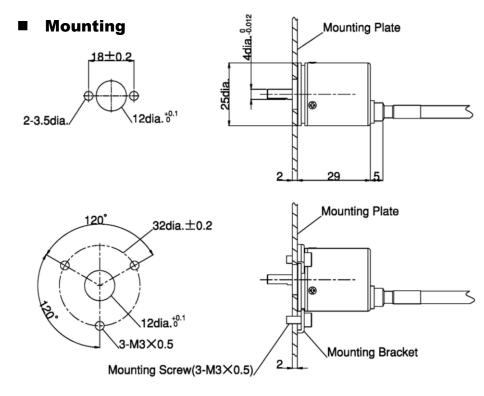
| Ambient | Operation | −10~+70°C | | |
|-------------------|-----------|--|---|--|
| temperature Store | | -25~+85°C | | |
| Ambient hu | midity | 35~85%RH (non-condensing) | | |
| Withstand v | roltage | Grounded through capacitor ⁵ | Power and signal lines are in the casing; | |
| Insulation res | istance | 20MΩ min. | Shield line is not in the casing | |
| Vibration resi | stance | 10 to 55Hz with 0.75mm amplitude ^{⁺6} | | |
| Shock resis | stance | 11ms with 490m/s ² ^{*7} | | |
| Protection cor | struction | IP50 (Dust proof) | | |

TRD-MXDV

*5: A capacitor of 0.01µF/630V is connected between 0V and FG lines.

*6: Durable for 1h along 3 axes) It is an examination condition, and it can not *7: Applied 3 times 3 axes ∫ guarantee for consecutive use



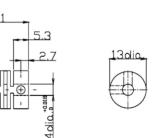


Options

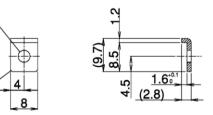
2.7

4 dia.0

Coupling(GJ-4)



Mounting bracket(MM-4)





<u>4-M3 set screw</u>

| Type No. Material | | α | 3 | S |
|-------------------|-----------|--------|----------|-----------|
| GJ-4 | PBT resin | 5° MAX | 0.5mmMAX | 0.12mmMAX |

3.5dia.

2-C0.5