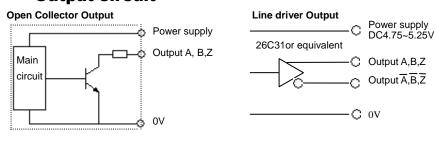


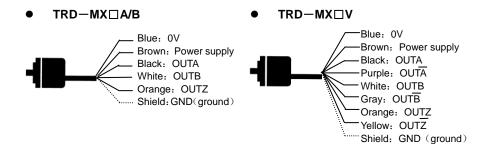
Electrial specifications

Type No.

Output circuit



Connection



	21				
	Operating voltage ^{*1}		A: 4.5V~13.2V DC	4.75V~5.25V DC	
Power			B: 10.8V~26.4V DC		
supply Allowable ripple		pple	3%rms Max.	3%rms Max.	
	Current consumption(no load)		50mA Max.	50mA Max.	
	Signal format		Quadrature output	Quadrature output	
Output waveform	Max. response frequency		100kHz	100kHz	
	Operating speed		(Maximum response frequency/Pulse) $ imes$ 60	(Maximum response frequency/Pulse)×60	
	Symmentry		50±25%	50±25%	
	Index signal width		100±50%	100±50%	
Output	Rising/falling time ^{*2}		2µs Max.	2µs Max.	
	Output configuration		NPN open collector	Line driver (26C31 or equivalent)	
	Output logic		Negative logic (active low)	Positive logic (active high)	
	Output current	Inflow	30mA Max.		
		Outflow	_	20mA Max.	
		"H"	_	2.5V Min.	
	Output voltage	"L"	0.4V Max.	0.5V Max.	
	Load power supply voltage		DC30V Max.	_	

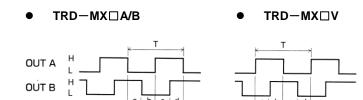
TRD-MX A/B

*1: To be supplied by class $I\!I$ source

*2: With a cable of 1m or less.Maximum load.

Output signal timing chart

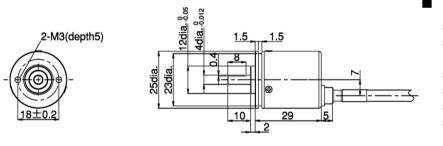
(CW rotation viewed from input-shaft of encoder)



a,b,c,d=(25±12.5%)T

External dimensions

OUT Z



Mechanical specifications

Startin	Max. 0.001N • m (+20°C)		
Shaft mom	$1 \times 10^{-7} \mathrm{kg} \cdot \mathrm{m}^2$		
	Radial	10N	
Max. allowable shaft load	Thrust	5N	
Max.allow	6000rpm		
	Material	Oil-resistant PVC ^{*3}	
Cable	Nominal core cross section	0.14mm ²	
	External diameter	5.0mm	
We	Approx.0.08kg*4		

^{*3} MX A/B: 5-core shielded cable (AWG26)

 $\mathsf{MX} \square \mathsf{V}~$: 8-core shidlded cable (AWG26)

*4 with 1m cable

Cautions for use

- Do not wire the cable in parallel with other power lines and do not share a duct with other cables.
- Use capacitors or surge absorption elements to remove the sparks caused by relays and switches in the control panel as far as possible.
- Be sure to connect all wires properly, as wrong wiring can damage the internal circuitry.
- Erroneous pulses may be caused at the time of power ON and power OFF. After power ON, wait for at least 0.5 sec before use. Do not disassemble the product.
- As the rotary encoder is composed of precision parts, its function will be impaired when it is subjected to shocks. Use sufficient care for handling and mounting.

Environmental requirements

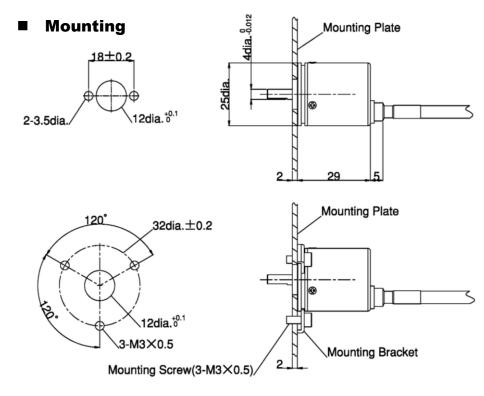
Ambient	Operation	−10~+70°C		
temperature Store		-25~+85°C		
Ambient hu	midity	35~85%RH (non-condensing)		
Withstand v	roltage	Grounded through capacitor ⁵	Power and signal lines are in the casing;	
Insulation res	istance	20MΩ min.	Shield line is not in the casing	
Vibration resi	stance	10 to 55Hz with 0.75mm amplitude ^{⁺6}		
Shock resis	stance	11ms with 490m/s ² ^{*7}		
Protection cor	struction	IP50 (Dust proof)		

TRD-MXDV

*5: A capacitor of 0.01µF/630V is connected between 0V and FG lines.

*6: Durable for 1h along 3 axes) It is an examination condition, and it can not *7: Applied 3 times 3 axes ∫ guarantee for consecutive use



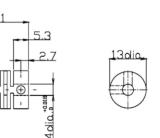


Options

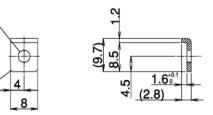
2.7

4 dia.0

Coupling(GJ-4)



Mounting bracket(MM-4)





<u>4-M3 set screw</u>

Type No. Material		α	3	S
GJ-4	PBT resin	5° MAX	0.5mmMAX	0.12mmMAX

3.5dia.

2-C0.5